



**LITHOFLEX WORKSHOP**  
24-25 JUNE 2008



**StatoilHydro Research Centre Rotvoll –  
Trondheim – Norway**

**Lithoflex theoretical background- Part I:  
Theoretical background for gravity  
studies**

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With the cooperation of

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**StatoilHydro**

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**Course Program**



**Day 1 Morning- theory (9:00-11:30)**

9:00-9.15: Welcome

**9.15-10:15: Part I: Theoretical background for gravity studies  
(CB)**

Theoretical background for gravity forward and inverse calculation by Parker approach. Role of the minimum wavelength in inversion. Parameter trade-off. Sensitivity study of parameters. Grace derived gravity field; GOCE satellite

10:15-10.30: Coffee

**10:30-11:30: Part II: Density-depth functions (JE)**

Density-depth functions in general and for sediments. Velocity-depth relation. Compaction models.

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### **Day 1 Afternoon- practical (12:30-16:00)**

12:30-13:15

-Data preparation. Useful grid sampling. Geosoft and Surfer Grid formats (JE)

14:00-...

Areas to be calculated: 1 - West Siberian Basin.

Introduction to grids: sediment, topography, gravity anomaly, Bouguer anomaly, Moho, seismic sections (Vyssotski). Sediment forward calculation. Testing different density-depth functions. Moho forward gravity calculation, Testing of parameters, gravity residual calculation

(2 - Backup example: South China Sea)

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### **Day 2 Morning- theory (9:00-11:30)**

9:00-9:30: **Part III Introduction to isostasy (SW)**

9:30-10:15: **Part IV Isostatic anomalies and basin evolution (JE)**

isostatic anomalies, local isostasy, Pratt model, McKenzie-rifting, Backstripping

10:15-10:30: Coffee

10:30-11:30: **Part V Regional flexure modelling (CB)**

Regional flexure modelling, full plate and broken plate model, Te constant and variable, Forward and inverse flexure calculations, Necessary constraints: crustal thickness and equivalent load, relative importance of internal loads and topographic loads (CB).

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### **Day 2 Afternoon- practical (12:30-15:00)**

equivalent total load calculation. Synthetic topographic generation. Flexure forward calculation. Continue flexure forward calculation, testing role of parameters. Flexure inverse calculation on a synthetic case.

### **Final Discussion.**

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## **Topics**

- Motivation for Lithoflex
- Theoretical background for gravity forward and inverse calculation by Parker approach.
- Main parameters
- Sensitivity study of parameters.
- Grace derived gravity field.
- GOCE satellite.

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## Motivation of isostatic-gravity joint study- Lithoflex approach

- For practical interest: detailed knowledge of small area
- But profitable:
  - knowledge of broader geological context.
  - knowledge of geological boundaries

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## Example boundaries

- Ocean-continent crustal boundary
- Ancient plate boundaries
- Ancient deformation zone
- Mobile belts
- Suture zones
- Rift sequences
- Rifted crust

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## Isostasy and gravity in identifying boundaries

- Assumption:
  - Lithospheric rheology: boundaries may produce differences in physical properties
- In particular of our interest:
  - flexural rigidity
  - density variation

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## Flexure model

- Deformation of thin elastic plate.
  - "thin": horizontal layers remain parallel
  - Details on Tuesday
- If a vertical density gradient is present: deformation produces measurable gravity signal.

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## Vertical density gradients

- Main vertical density gradients in normal conditions:
  - Topography/bathymetry
  - Sediments/basement
  - Crust-Mantle-boundary
- Flexed crust: deformed density boundary layers

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## Evaluate gravity of flexed crust

- Direct approach:
  - Evaluate gravity field of surface with strong density gradient
  - Series expansion due to Parker
- Gravity modeling situations:
  - Inverse: determine undulation of boundary, compare with the expected flexure
  - Forward: you have calculated flexure of crust, determine the corresponding gravity signal
- -> examples in the PC-application this afternoon.

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# Gravity signal

- Gravity signal of an undulating boundary:

$$FT[\Delta g(\vec{r})] = 2\pi G e^{-|\vec{k}|d} \sum_{n=1}^{\infty} \frac{|\vec{k}|^{n-1}}{n!} FT[w_d^n(\vec{r}) \Delta \rho(\vec{r})]$$

Gravity field of a layer bounded by upper and lower surface

$$FT[\Delta g(\vec{r})] = 2\pi G e^{-|\vec{k}|d} \sum_{n=1}^{\infty} \frac{|\vec{k}|^{n-1}}{n!} FT[(z_U^n(\vec{r}) - z_L^n(\vec{r})) \rho(\vec{r})]$$

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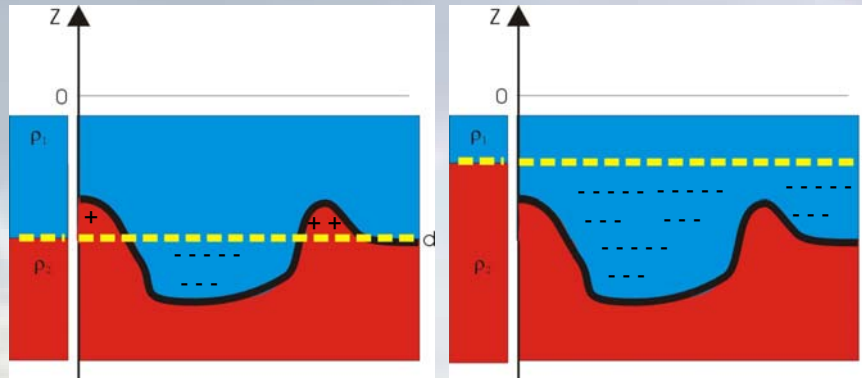
## Parameters entering the gravity field calculations

- Boundary forward modeling depends on:
  - Reference depth d
  - Density contrast
- Boundary inverse modeling depends on:
  - Reference depth d
  - Density contrast
  - Filtering cut-off wavelength Pmin

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# Role of reference depth

forward or inverse calculation



$$\rho_2 > \rho_1$$

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# Role of reference depth

gravity inversion

- Effects of reference depth **d**:
  - Shift undulation of boundary vertically
  - Damping of higher wavenumbers
  - For increasing density with depth:
    - boundary above **d**-> positive gravity effect.
    - boundary below **d**-> negative gravity effect
- Notice: **d** not necessarily average depth of layer

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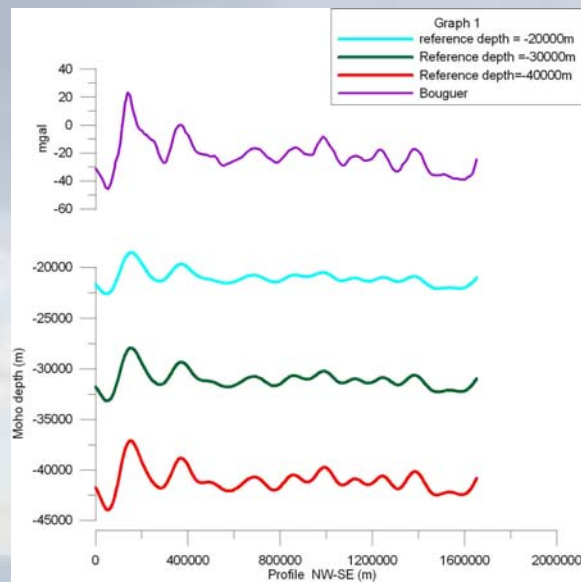




## Reference depth gravity inversion



Graph showing inversion for different reference depths. Notice Amplitude increase of solution for increasing reference depth.



## Amplitude dependence of reference depth



- For inversion process:
- Focus on:
  - wavelength dependency of amplitude of boundary undulation

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## Gravity signal and depth of sources

- Earth filter: high spatial frequencies are reduced for increasing source-distance
- What is minimum amplitude placed at Moho level to be detected?

$$FT[\Delta g(\vec{r})] \approx 2\pi G(\rho_m - \rho_c) e^{-|\vec{k}|d} FT[w(\vec{r})]$$

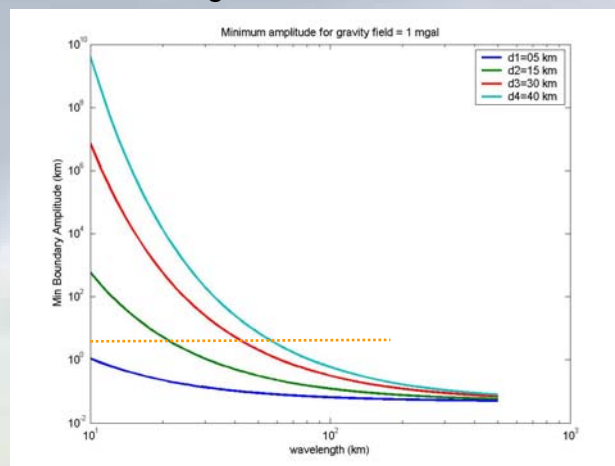
$$w_k = \Delta g_k \frac{e^{|\vec{k}|d}}{2\pi G(\rho_m - \rho_c)}$$

With  $w_k$  and  $\Delta g_k$  the spectral components of the respective fields for wavenumber  $k$

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## Amplitude estimates

- Gravity resolution=1 mgal, different source-depths, variable wavelengths



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## Consequences for inversion process



- Observed field must be frequency limited prior inversion.
- Low pass filter.
  - Cut off wavelength  $P_{min}$ .
- Next slide:
  - resulting boundary for different choices of  $P_{min}$ .

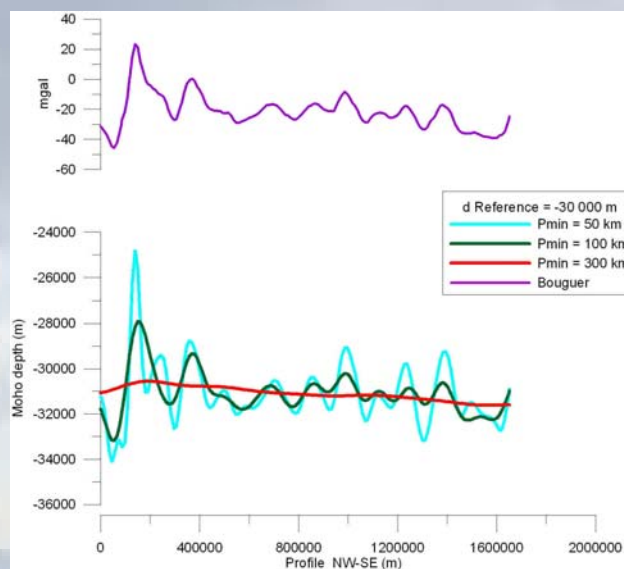
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## Cut-off wavelength



Graph showing inversion for different  $P_{min}$ . A small  $P_{min}$  erroneously projects superficial masses to Moho level.





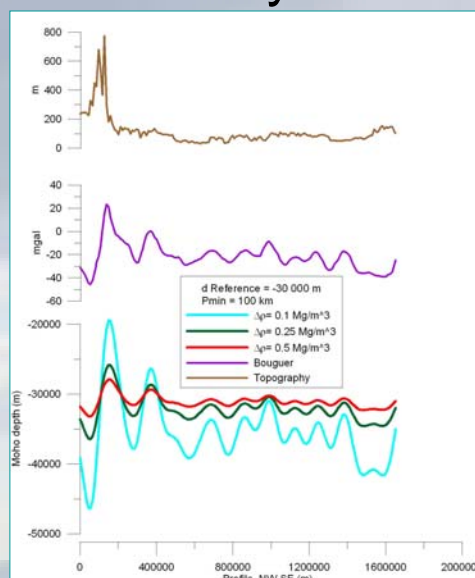
## Density

- Density enters calculation as difference between upper and lower layer
- Solution inversely proportional to density contrast

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## Effect of density variation



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## Pitfalls in the inversion

- Gravity inversion: given the model, a solution is found. Only the control with the constraining data or physical model assures solution is correct.
- Operator's responsibility: isolate signal produced by the boundary undulation
  - Forward calculation of known masses: topography/bathymetry, sediments, rifts
  - Frequency filtering of signal

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## Pitfalls in gravity inversion

- Low pass filtering not necessarily eliminates superficial masses  
Examples:
  - large sediment basin
- Safely: high frequency-gravity field comes from superficial sources.

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## Forward calculation

- Less problematic.
- Only choice of reference boundary and density contrast necessary.
- Observations made for inversion process easily projected into forward calculation process.

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## Part B of seminar

- A look on global modern gravity fields
- Recent fields derived from satellite GRACE
- Outlook on the new expected developments from GOCE

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## Modern global gravity fields

- GRACE satellite derived fields
  - Pure satellite derived field: N=150
  - Coefficients of higher order: integration of satellite and terrestrial data.
- Max degree and order N: refers to spherical harmonic development

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## Spherical harmonic development

$$U(r, \vartheta, \lambda) = \frac{GM}{r} \left( 1 + \sum_{n=1}^{\infty} \sum_{l=0}^n \left( \frac{a}{r} \right)^n (C_{nl} \cos l\lambda + S_{nl} \sin l\lambda) P_{nl}(\cos \vartheta) \right)$$

$M$  = Earth mass     $G$ =Gravitational constant

$a$ = equatorial radius

$C_{nl}$ ,  $S_{nl}$ : Harmonic coefficients (Stokes coefficients)

$P_{nl}(\cos \vartheta)$ : Associated Legendre Polynomials

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## Degree and order

- Degree  $N$ , order  $L$
- Spatial resolution:
- The maximum degree  $N$  of the expansion correlates to the spatial resolution at the Earth surface by

$$\lambda_{min} \approx 40000 \text{ km}/N$$

$$N=360$$

$$N=120$$

$$N=2160$$

$$\lambda_{min}=110\text{km}$$

$$\lambda_{min}=330\text{km}$$

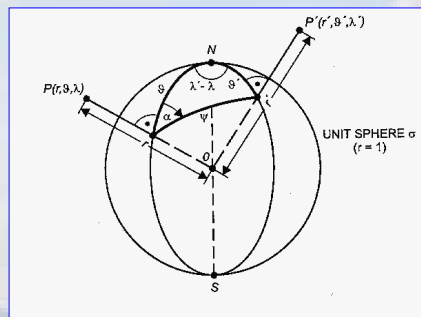
$$\lambda_{min}=19\text{km}$$

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## Stokes coefficients

$$C_{n0} = \frac{1}{M} \iiint_{\text{Earth}} \left( \frac{r'}{a} \right)^n P_n(\cos \vartheta') \rho(r', \vartheta', \lambda') dV$$

$$\begin{Bmatrix} C_{nl} \\ S_{nl} \end{Bmatrix} = \frac{2}{M} \frac{(n-l)!}{(n+l)!} \iiint_{\text{Earth}} \left( \frac{r'}{a} \right)^n P_{nl}(\cos \vartheta') \begin{Bmatrix} \cos l\lambda' \\ \sin l\lambda' \end{Bmatrix} \rho(r', \vartheta', \lambda') dV \quad \text{for } l \neq 0$$







## Satellite method



**Input data:** *Perturbations of satellite orbits*

Practical solution – **terrestrial gravity data, altimetry**

**Principle of the method:**

*Determination of spherical harmonic coefficients using perturbations of satellites*

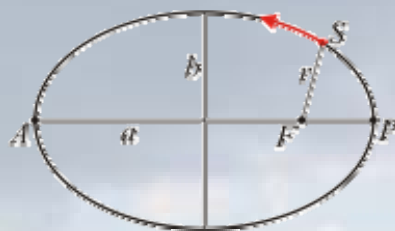


(Michal Sprlak, 2008)

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**HYPOTHESIS:** Earth is homogeneous sphere, no sun and moon exist, no atmosphere



**NO PERTURBATIONS ON SATELLITE ORBIT!!!**

**NO CHANGE OF ORBITAL ELEMENTS!!!**

*Gravitational potential on orbit:*

$$V(S) = \frac{GM}{r}$$



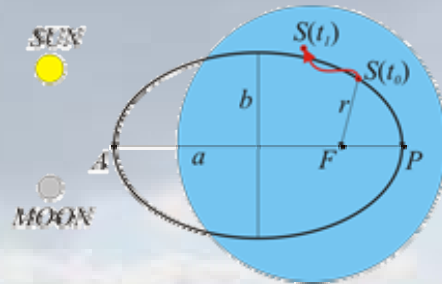
(Michal Sprlak, 2008)

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**REALITY:** Earth is heterogeneous body, sun, moon  
and atmosphere exist



**PERTURBATIONS ON  
SATELLITE ORBIT!!!**

**CHANGE OF ORBITAL  
ELEMENTS!!!**

*Gravitational potential on orbit:*

$$V(S) = \frac{GM}{r} \left\{ 1 + \sum_{n=1}^{\infty} \sum_{m=0}^n \left( \frac{a}{r} \right)^n \left[ C_{nm} R_{nm}(\varphi, \lambda) + S_{nm} S_{nm}(\varphi, \lambda) \right] \right\}$$

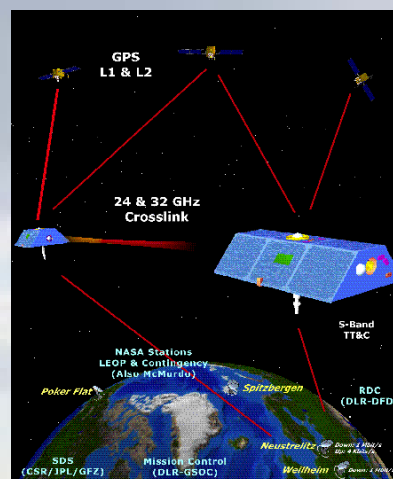


(Michal Sprlak, 2008)

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## GRACE satellite mission Gravity Recovery And Climate Experiment



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## GRACE satellite mission

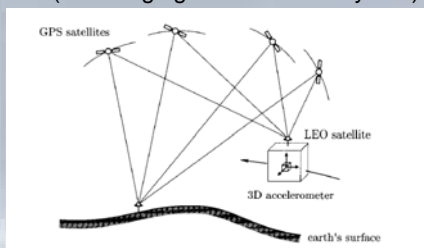
- GRACE satellite: launch March 17, 2002.
- $H=500$  km
- Satellite separation: 200 km along track.
- Distance and rate changes measurement: K-band microwave ranging system.
- Further: GPS receiver, Laser-retro-reflector, star-sensors, three-axis accelerometer

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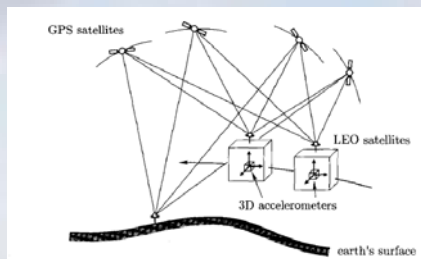


## Satellite observations

CHAMP  
(Challenging Minisatellite Payload)



GRACE



SST-hl: Satellite-Satellite Tracking in high-low mode  
SST-ll: Satellite-Satellite Tracking in low-low mode  
LEO: Low Earth orbit satellite

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## Current global gravity fields

- EIGEN-GL04C (Förste et al., 2008): N=360
- EGM2008 (Pavlis et al., 2008): N=2160
- EGM96 (Lemoine et al., 1998): N=360

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## Calculation methodology of EIGEN-GL04c

- Dynamic approach based on analysis of orbit perturbations of GRACE and LAGEOS satellites  $n < 150$
- $N > 120$ : Compilation of surface gravity data: satellite altimetry, ship-borne/airborne gravity over oceans
- Airborne + terrestrial over land: 30'x30' grid

Förste et al., 2008



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## Data sources for EIGEN-GL04c

- Terrestrial principal source: NGA (Nat. Geospatial Intelligence Agency, former NIMA) 30'x30' grid
- OCEAN: GFZ Mean Surface height (ERS-1, ERS-2, Topex/Poseidon) minus ECCO Circulation model of oceanic surface.
- Satellite field: 2 years of GRACE data (2002-2005)

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Practical solution:

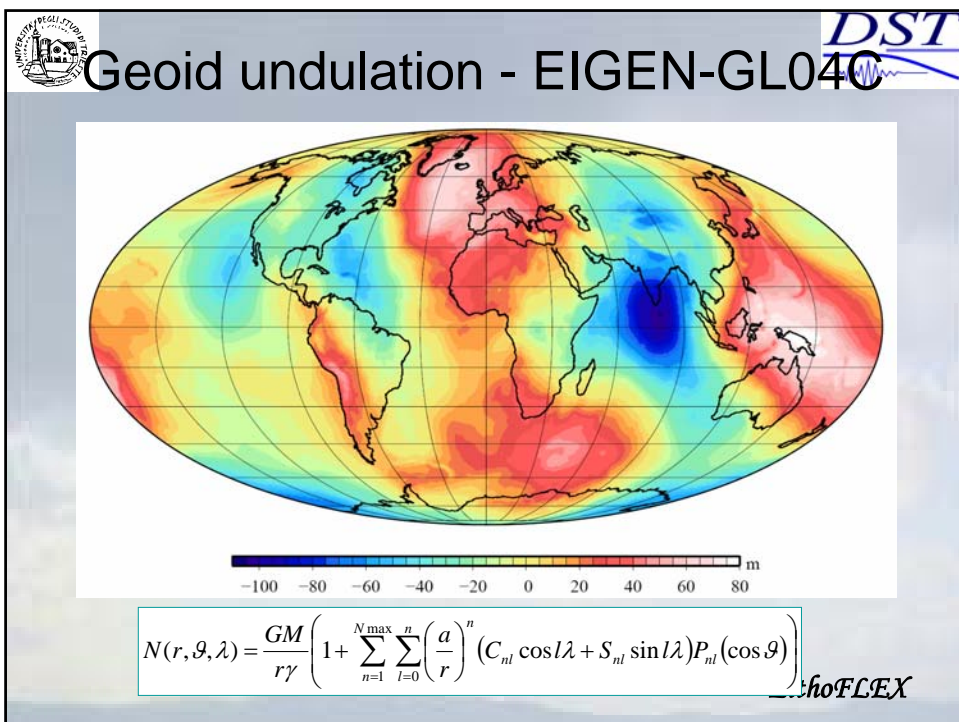
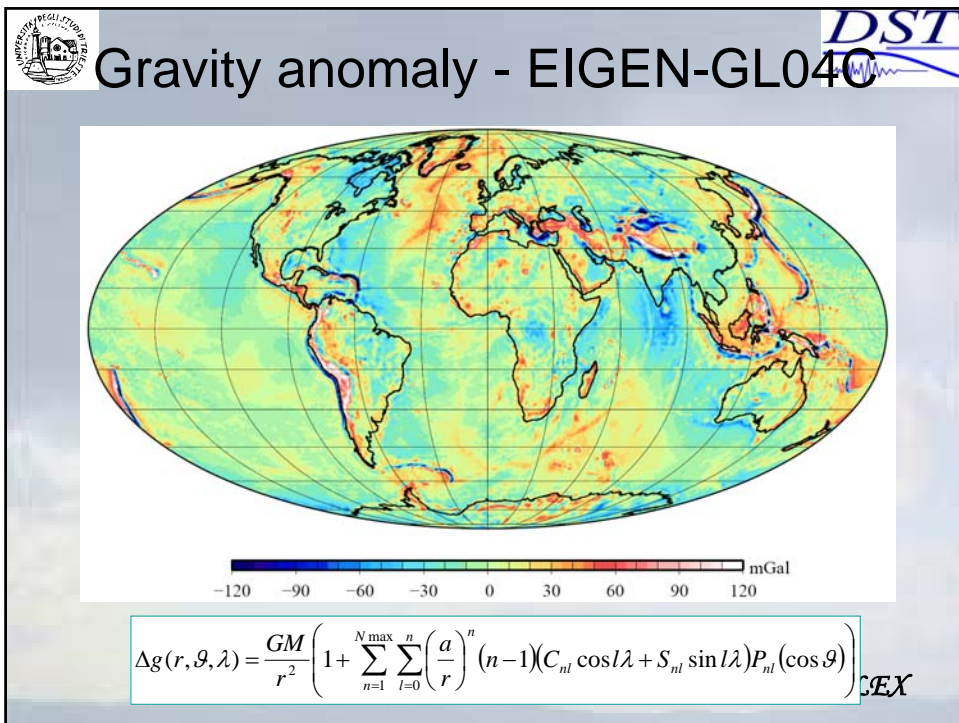
### GLOBAL GRAVITY FIELD MODELS

- pure satellite
- combined

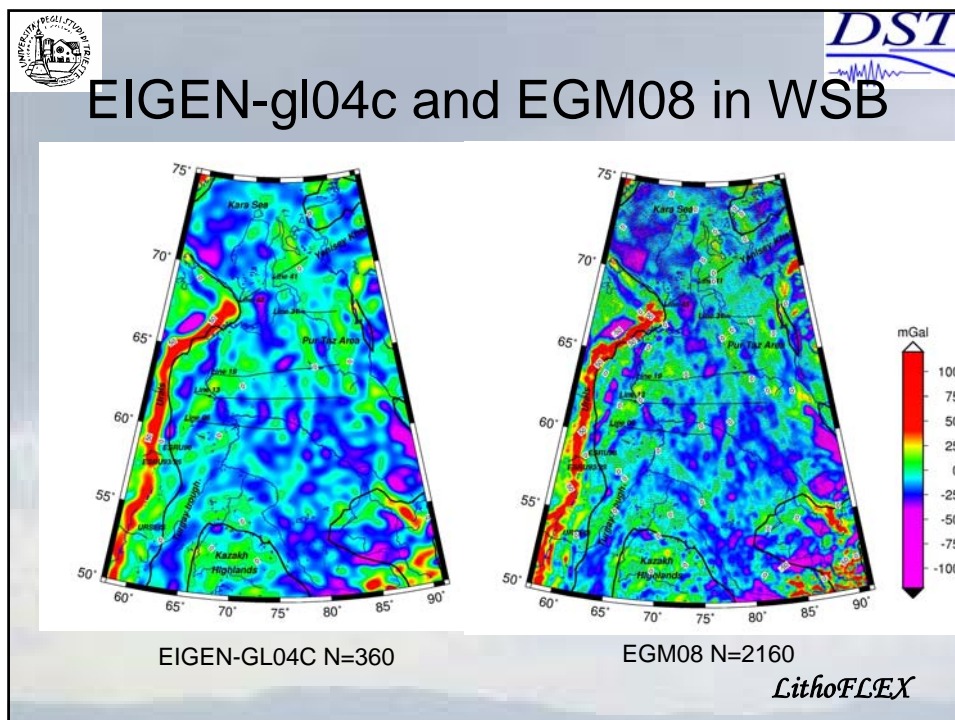
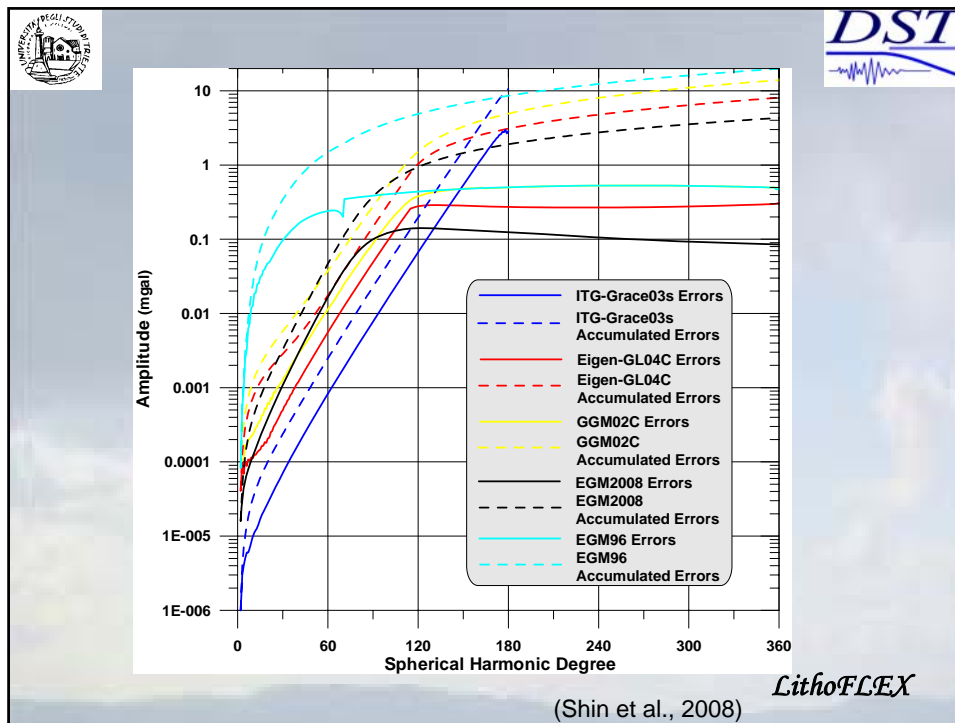
EIGEN-GL04C potential coefficients up to degree and order 360.

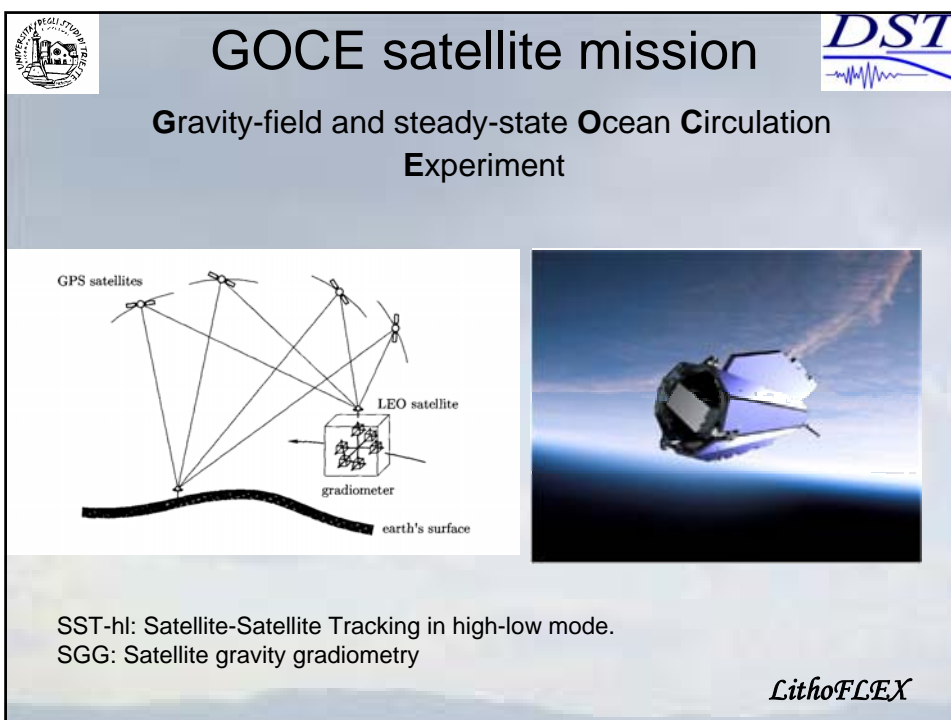
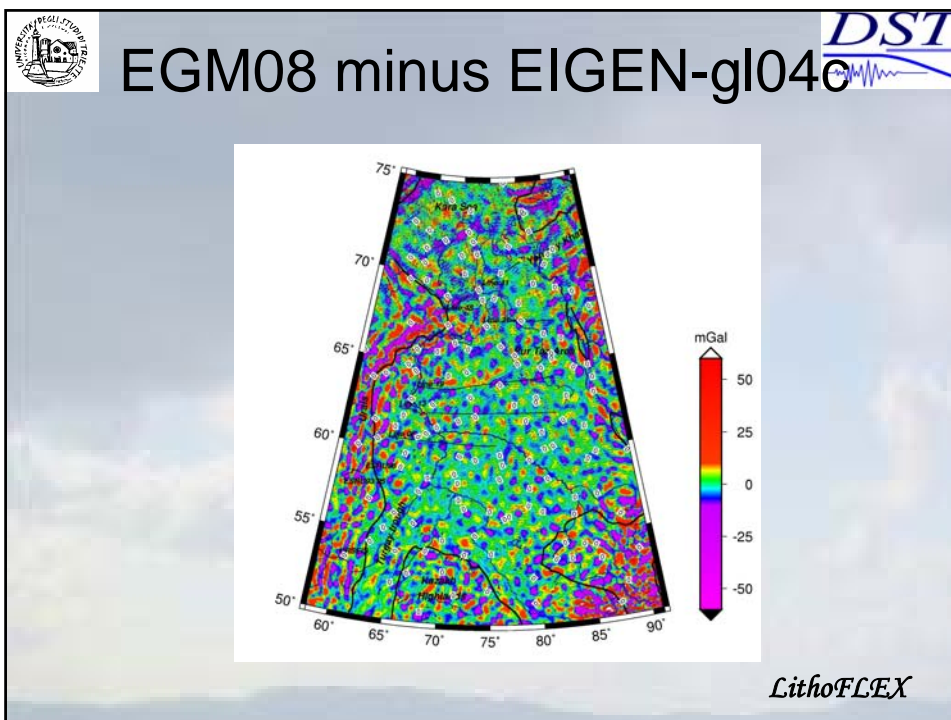
360	6378136.3	0.3986004415E+15			
2	0	-0.484165371736E-03	0.000000000000E+00	0.35610635E-10	0.00000000E+00
2	1	-0.186987635955E-09	0.119528012031E-08	0.10000000E-29	0.10000000E-29
2	2	0.243914352398E-05	-0.140016683654E-05	0.53739154E-10	0.54353269E-10
3	0	0.957254173792E-06	0.000000000000E+00	0.18094237E-10	0.00000000E+00
3	1	0.202998882184E-05	0.248513158716E-06	0.13965165E-09	0.13645882E-09
3	2	0.904627768605E-06	-0.619025944205E-06	0.10962329E-09	0.11182866E-09
3	3	0.721072657057E-06	0.141435626958E-05	0.95156281E-10	0.93285090E-10
4	0	0.539873863789E-06	0.000000000000E+00	0.10423678E-09	0.00000000E+00
4	1	-0.536321616971E-06	-0.473440265853E-06	0.85674404E-10	0.82408489E-10
4	2	0.350694105785E-06	0.662671572540E-06	0.16000186E-09	0.16390576E-09
4	3	0.990771803829E-06	-0.200928369177E-06	0.84657802E-10	0.82662506E-10
4	4	-0.188560802735E-06	0.308853169333E-06	0.87315359E-10	0.87852819E-10

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## GOCE characteristics

- Goal: determine stationary gravity field
- Accuracy 1 mgal, Geoid 1-2 cm, 100 km resolution
- Low orbit (250 km), almost polar
- Measurement: Gradiometer and position
- Position: high-low satellites (GPS and GLONASS) and IGS terrestrial permanent stations
- Error in position: cm-level in 3D.

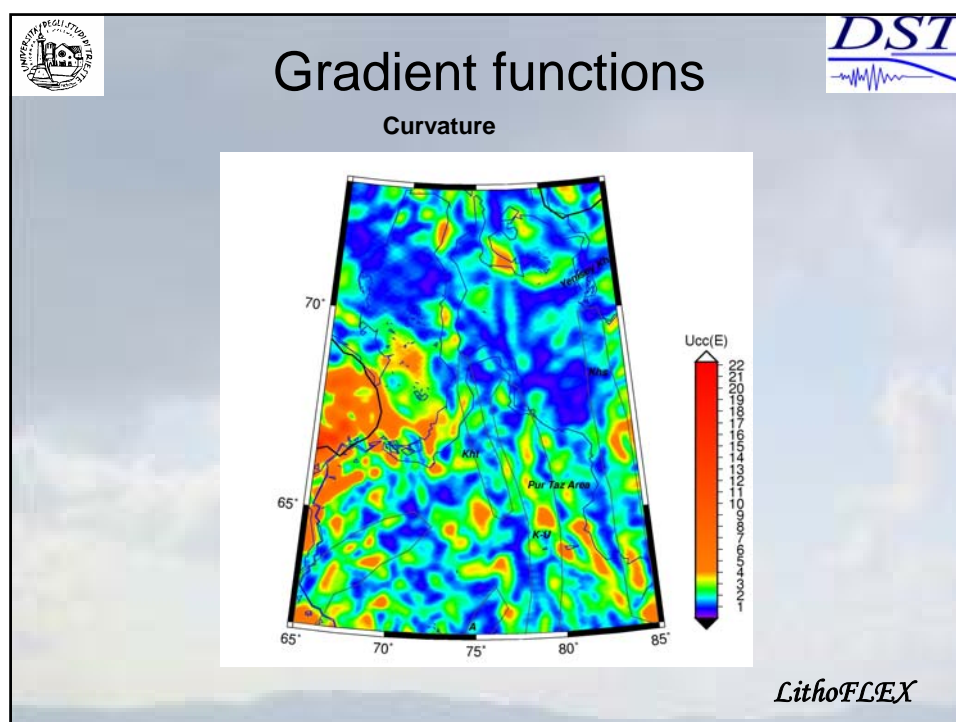
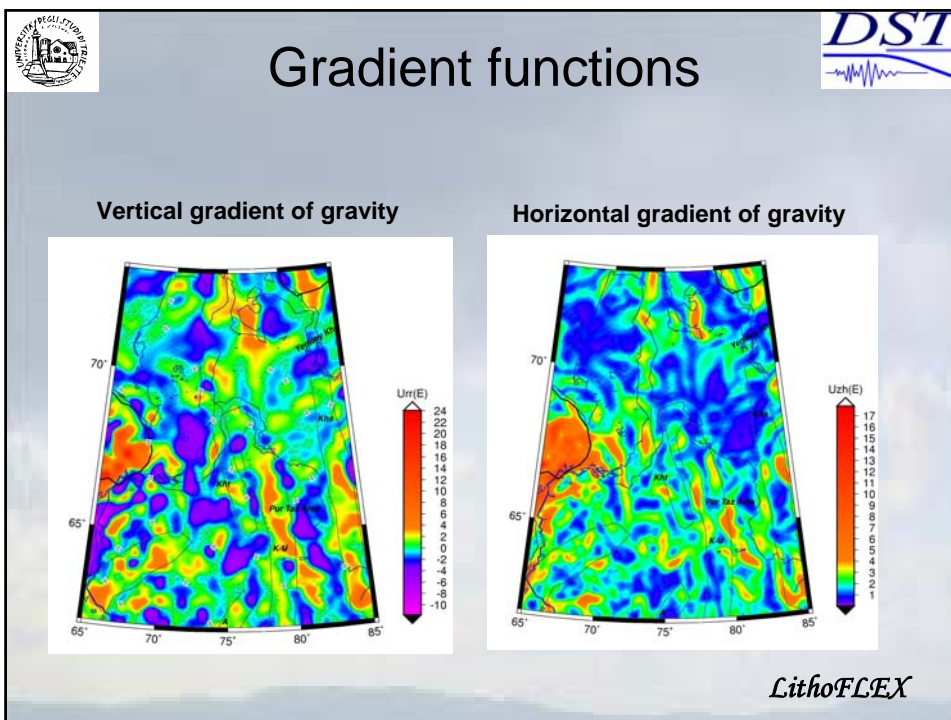
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## GOCE characteristics

- Non-gravitational forces corrected from on-board accelerometer measurements
- Satellite only field: up to degree and order  $n=200-250$  (according to reference)
- Gradiometer:
  - 3-axis. 6 capacitive accelerometers
  - Gradient error:  $60 mE / \sqrt{Hz}$
  - 1 Eötvös (E) =  $10^{-9} m/s^2/m = 10^{-7} Gal/m$
  - $V_{zz}$  = vertical gradient on Earth = 3000 E

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## Summary 1

- Needed for flexure calculations: gravity field of boundary
- Control correctness of crustal internal loads
- Crustal internal load: integration of density anomalies
- Parameters:
  - depth of boundary
  - Density contrast at boundary

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## Summary 2

- Global gravity fields: GRACE satellite-terrestrial integration
- New: improvement of harmonics  $<120$ .
- Affects global field accuracy
- EGM 2008: examples from West Siberian Basin.
  - Seems to have problems at high latitudes.
  - Striped anomalies. Satellite tracks evident in solution-> interpolation problem?

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## Summary 3

- GOCE
  - Launch september 2008
  - improvement of gravity field and geoid. Satellite-only up to  $N=200-250$
  - Tensor components at satellite height
  - examples of tensor components for Pur Taz area, West Siberian Basin.

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Thank you for your attention!



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